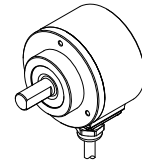


1. SS58 Sin/Cos Optical Encoder (Solid shaft)

1.1 Introduction:

This product is a solid shaft rugged enclosure design, can output 1024 or 2048 Sin/Cos period signal, a variety of mounting flange and collars, protection grade IP65, the product structure is compact, high safety, suitable for high intensity mechanical movement and high resolution segmentation field.

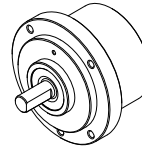
SS58-A



1.2 Feature:

- Encoder external diameter Ø58mm、thickness 36-40mm、diameter of shaft of Ø6mm、Ø8mm、Ø10mm available;
- Various sizes of mounting flanges available;
- Adopt non-contact photoelectric principle;
- Resolution per turn Sin/Cos period 1024 or 2048;
- Reverse polarity protection ;
- Short circuit protection.

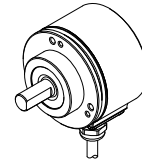
SS58-B



1.3 Application:

Motor,elevator,CNC and other automation control fields.

SS58-C



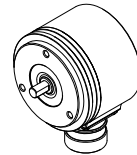
1.4 Connection:

- Cable connection (Standard length 1000mm)
- Socket connection (M12/M16/M23 male socket)

1.5 Protection:

IP65 (Max)

SS58-D

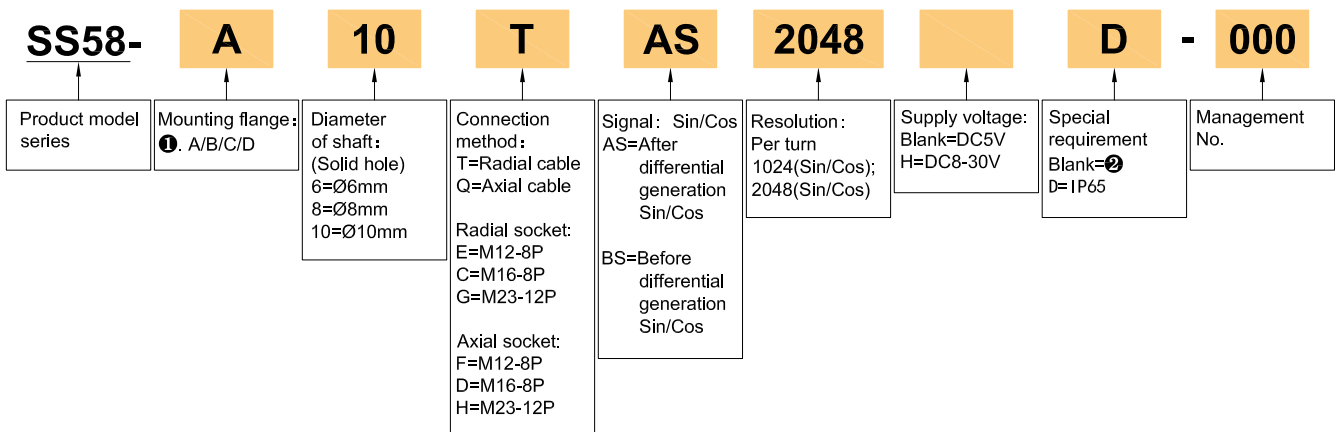


1.6 Weight:

About 420g

2. Model Selection Guide

Model composition(select parameters)



Mounting flange:

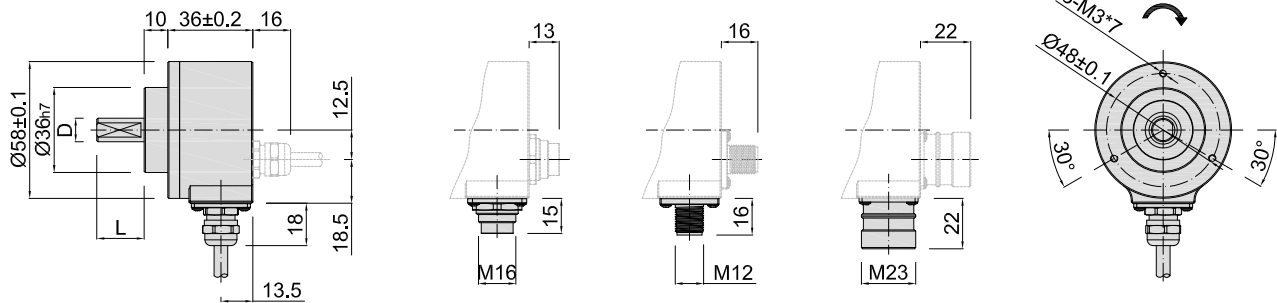
- ①. A=Clamping flange, collar Ø36mm, 3-M3 PCDØ48mm;
- B=Clamping flange, collar Ø56mm, 4-M4 PCDØ66mm;
- C=Synchro flange, collar Ø36mm, 3-M3 & 3-M4 PCDØ48mm;
- D=Synchro flange, collar Ø50mm, 3-M4 PCD42mm.

Special requirement:

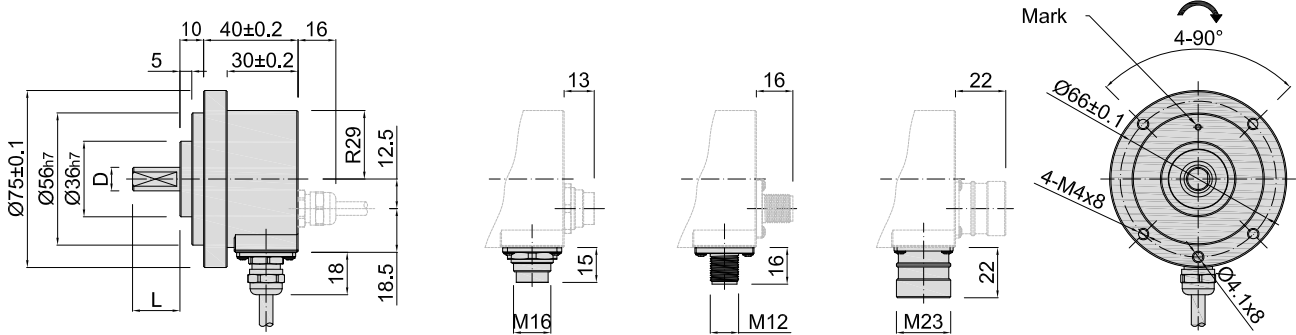
- ②. IP=50; cable length 1m, if need to change the length C+number, max 100m(indicated by C100).

3. Basic Dimensions

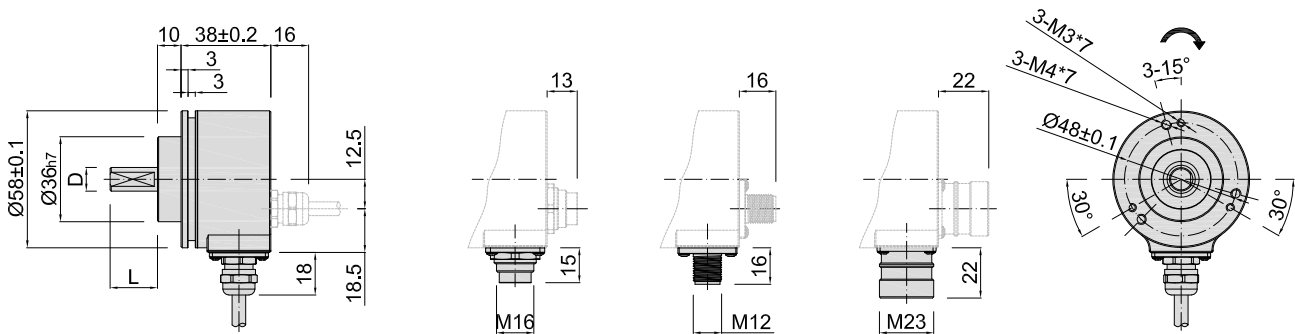
3.1 SS58-A (Basic dimensions)



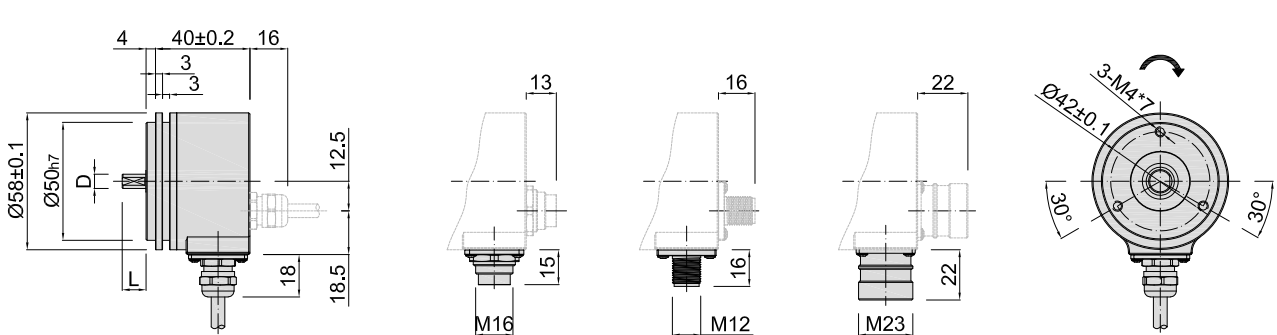
3.2 SS58-B (Basic dimensions)



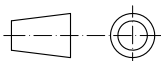
3.3 SS58-C (Basic dimensions)



3.4 SS58-D (Basic dimensions)



Unit: mm



= Direction of shaft rotation for signal output

D(Shaft)	Ø6 _{h7} (⁰ _{-0.015})	Ø8 _{h7} (⁰ _{-0.015})	Ø10 _{h7} (⁰ _{-0.018})
L	10	20	20

4. Technical Parameters

4.1 Performance

Sine/cosine periods per revolution	1024 & 2048
Measuring step	0,3 " Sin/Cos signals are subdivided by 12 bits ❶
Initialization time	50ms ❷
Integral non-linearity	Typ.±45 Winkelsekunden(Loose stator coupling)
Differential non-linearity	±7 Winkelsekunden
Reference signal, number	1
Reference signal, position	90°, electrically,gated with Sinus and Cosinus

❶. Not safety-related.

❷. Valid signals can be read thereafter.

4.2 Electrical Parameters

Communication interface	Incremental
Communication interface detail	Sin/Cos
Connection type	M12 & M16 8pin male socket; M12 & M23 12pin male socket; Cable connection (five options available)
Supply voltage	DC4.5V...5.5V; DC8V...30V
Maximum output frequency	≤200 kHz
Load resistance	≥120Ω
Power consumption max.(without load)	≤0,7 W
Power consumption	Without load
Reverse polarity protection	✓
Protection grade	IP50 & IP65
Short-circuit protection	✓ ❶

❶. Short-circuit to another channel or GND permitted for max.30s.

4.3 Mechanical Parameters

Diameter of shaft	Ø6mm; Ø8mm; Ø10mm available
Shaft material	Stainless steel
Starting torque	at +20°C IP50<0.05 Nm; IP65<0.1 Nm
Inertia moment	Less than 3×10^{-6} kg·m ²
Shaft load	Radial 60N; Axial 40N
Permissible movement static	±0.3mm (radial) ; ±0.5mm (axial)
Permissible movement dynamic	±0.05mm (radial) ; ±0.1mm (axial)
Max.angular acceleration	≤500,000 rad/s ²
Operating speed	6000min ⁻¹ ❶
Bearing lifetime	3.6×10 ⁹ ❷
Housing material	Aluminum alloy
Weight	Approx.420g

❶. Allow for self-heating of approx.3.0K per 1000rpm regarding the permissible operating temperature.

❷. On maximum operating speed and temperature.

4.4 Environmental Parameters

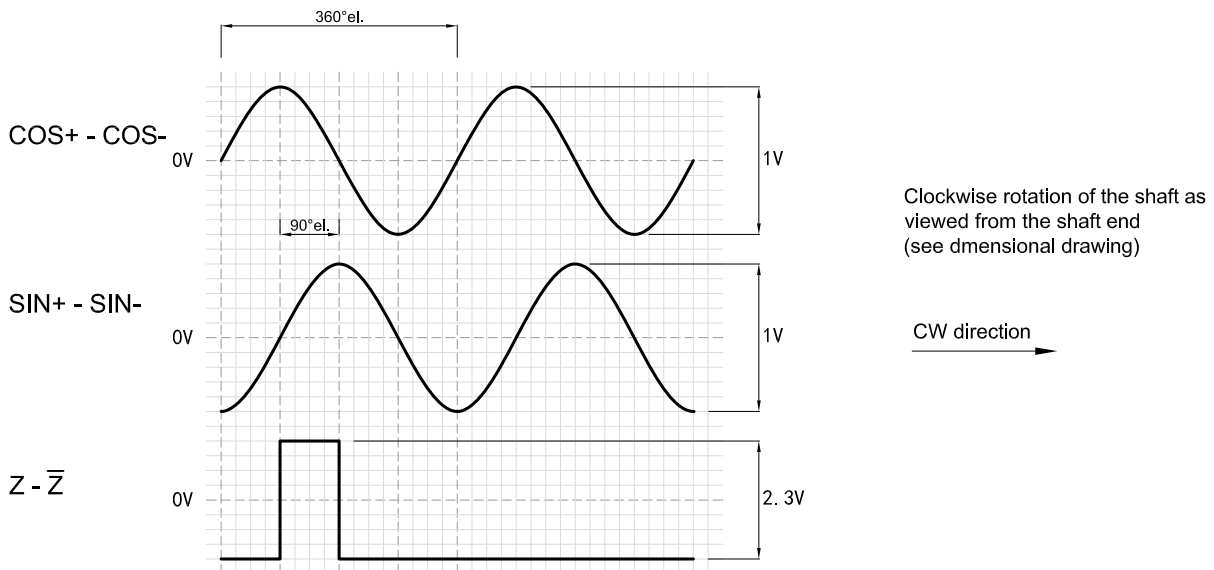
Shell protection grade	IP65 (Max)
Permissible relative humidity	90%,Condensation not permitted
Operating temperature range	-40°C...+95°C
Storage temperature range	-40°C...+95°C
Resistance to shocks	100g, 6ms(EN60068-2-27) ❶
Frequency range of resistance to vibrations	30g, 10Hz...1,000Hz(EN60068-2-6) ❷

❶. Checked during operation using vector length monitoring.

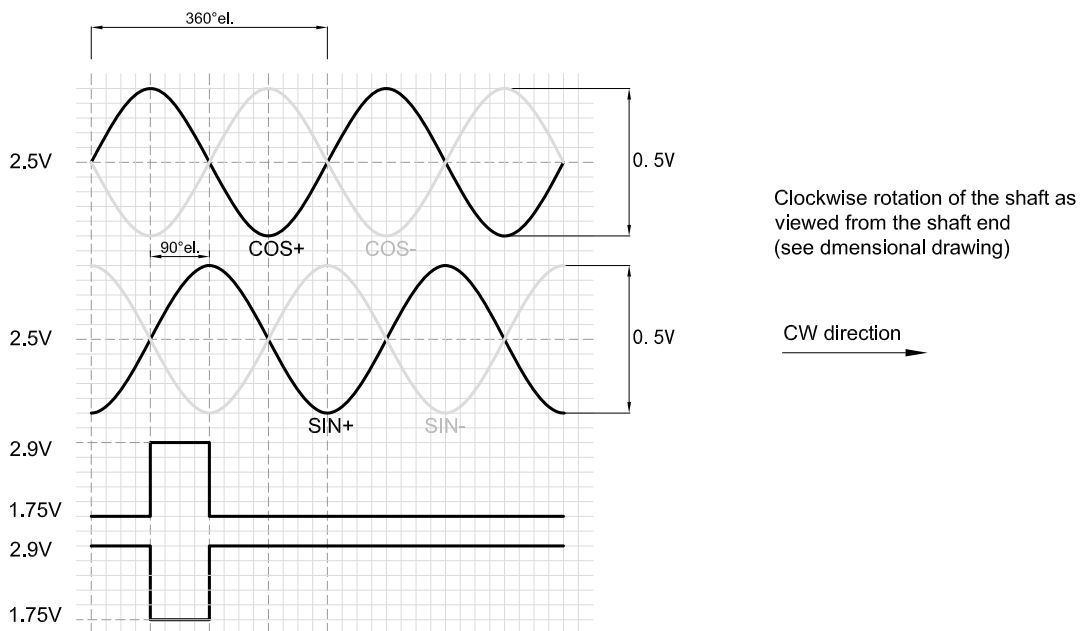
❷. Checked during operation using vector length monitoring, including matching plug.

5. Output wave form

5.1 Signal SIN/COS after differential generation



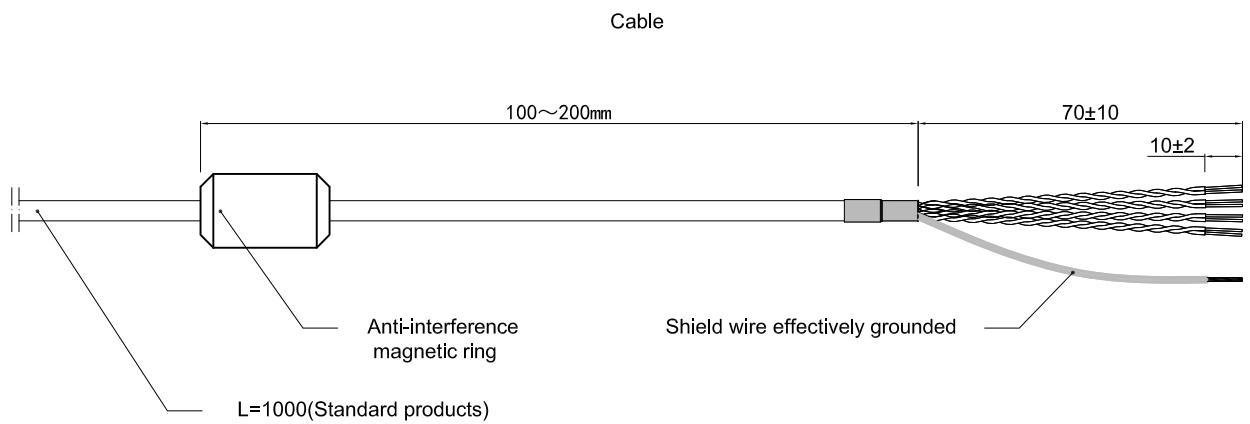
5.2 Signal SIN/COS before differential generation



Supply voltage	Signal	Interface signals	Interface signals after differential generation		Interface signals before differential generation	
			Output	Signal offset	Output	Signal offset
DC5V; DC8V...30V	+SIN -SIN +COS -COS	Analog,differential	SIN/COS 1.0 Vss	0V±10%	0.5Vss±20%	2.5V±10%
	Z Z̄	Digital,differential	Low:-1.15V±15%, High:1.15V±15%		Low:1.75V±15%, High:2.9V±15%	

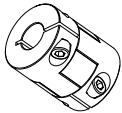
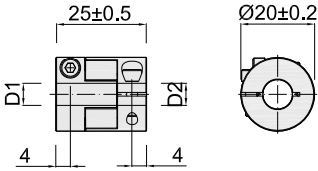

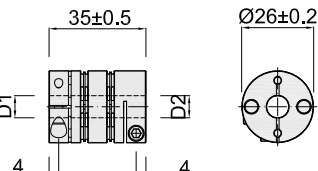
6. Wiring table

Socket pin definition (M12 8-pin)	Socket pin definition (M16 8-pin)	Socket pin definition (M23 12-pin)	Wire colors (cable connection)	Signal	Explanation	Twisted wire
1	1	6	White/BK	-COS	Signal wire	
2	2	5	White	+COS	Signal wire	
3	3	1	Green/BK	-SIN	Signal wire	
4	4	8	Green	+SIN	Signal wire	
5	5	4	Yellow/BK	\bar{Z}	Signal wire	
6	6	3	Yellow	Z	Signal wire	
7	7	10	Black	Un	Power negative	
8	8	12	Red	Up	Power position	
-	-	9	-	N.C.	Unallocated	
-	-	2	-	N.C.	Unallocated	
-	-	11	-	N.C.	Unallocated	
-	-	7	-	N.C.	Unallocated	
GND	No encoder body connected					

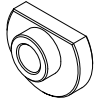
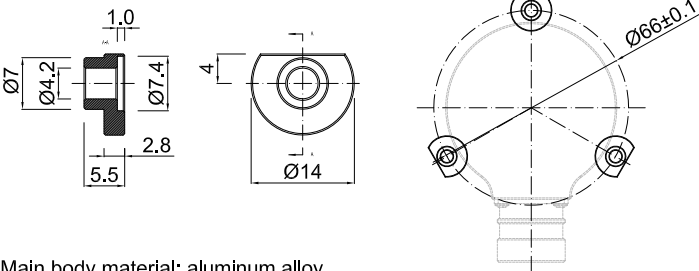


7. Recommended Accessories

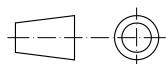
7.1 Coupler

Coupler	Dimensions	D1	D2	Model	Order No.
Cross type: M series 	 <p>Main body material: aluminum alloy</p>	Ø6 ^{G8}	Ø8 ^{G8}	6M8	08700038
		Ø8 ^{G8}	Ø8 ^{G8}	8M8	08700039
		Ø8 ^{G8}	Ø10 ^{G8}	8M10	08700040
Diaphragm type: W series 	 <p>Main body material: aluminum alloy</p>	Ø6 ^{G8}	Ø8 ^{G8}	6W8	08700042
		Ø8 ^{G8}	Ø8 ^{G8}	8W8	08700043
		Ø8 ^{G8}	Ø10 ^{G8}	8W10	08700044

7.2 Mounting cardboard

Mounting cardboard	Dimensions	Model	Order NO.
 <p>3 pcs as a set</p>	 <p>Main body material: aluminum alloy</p>	58C66	03700733

Unit: mm



8. Caution

8.1 Caution for operation

- The working temperature shall not exceed the storage temperature.
- The working humidity shall not exceed the storage humidity.
- Do not use where the temperature changes dramatically and have fog.
- Do not close to corrosive and flammable gas.
- Keep away from dust, salt and metal powder.
- Keep away from places where you will use water, oil, or medicine.
- Undue vibration and shock will impact the encoder.

8.2 Caution for Installation

- Electrical components should not be subjected to excessive pressure, etc., and electrostatic assessment of the installation environment should be conducted.
- Do not close the cable of the motor power to the encoder.
- The FG wire of the motor and mechanical device should be grounded.
- The shielding wire must be effectively grounded since the shielding is not connected to the encoder.

8.3 Caution for wiring

- Use the encoder under the specified supply voltage. Please note that the supply voltage range may drop due to the wiring length.
- Do not put the encoder wiring and other power lines through the same duct, and do not use them by bundling in parallel.
- Please use twisted pair wires for the signal and power wires of encoder.
- Please do not apply excessive force to the cable of encoder, or it will may be damaged.