

1. KM55 Multi-turn Absolute encoder (Through shaft)

1.1 Introduction

KM55 is a through shaft miniaturized design, high precision photoelectric absolute encoder, capable of outputting 24Bits of single-turn position information, expandable up to 32Bits, can read up to 24Bits of multi-turn position information. The structure is sturdy and durable.

1.2 Feature:

- External diameter Ø55mm、thickness 22mm、 diameter of shaft up to Ø25mm.
- Compact and sturdy structure.
- Adopt non-contact photoelectric reflection principle.
- Interface: BiSS_C or SSI.
- Accuracy: ±80".
- Single-turn resolution of 24Bits is expandable up to maximum 32Bits.
- Support multi-turn data recording without power failure, the maximum recording is 24 Bits.

1.3 Application:

Servo motor, robot and other industrial automations.

1.4 Connection:

- Radial socket (8P SM08B-GHS-TB)
- Radial cable (standard length 1000mm)

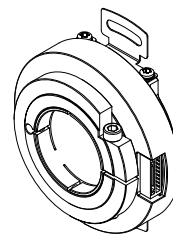
1.5 Protection:

IP50

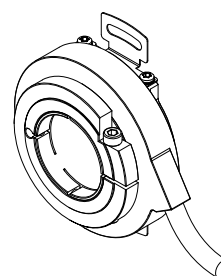
1.6 Weight:

about 150g

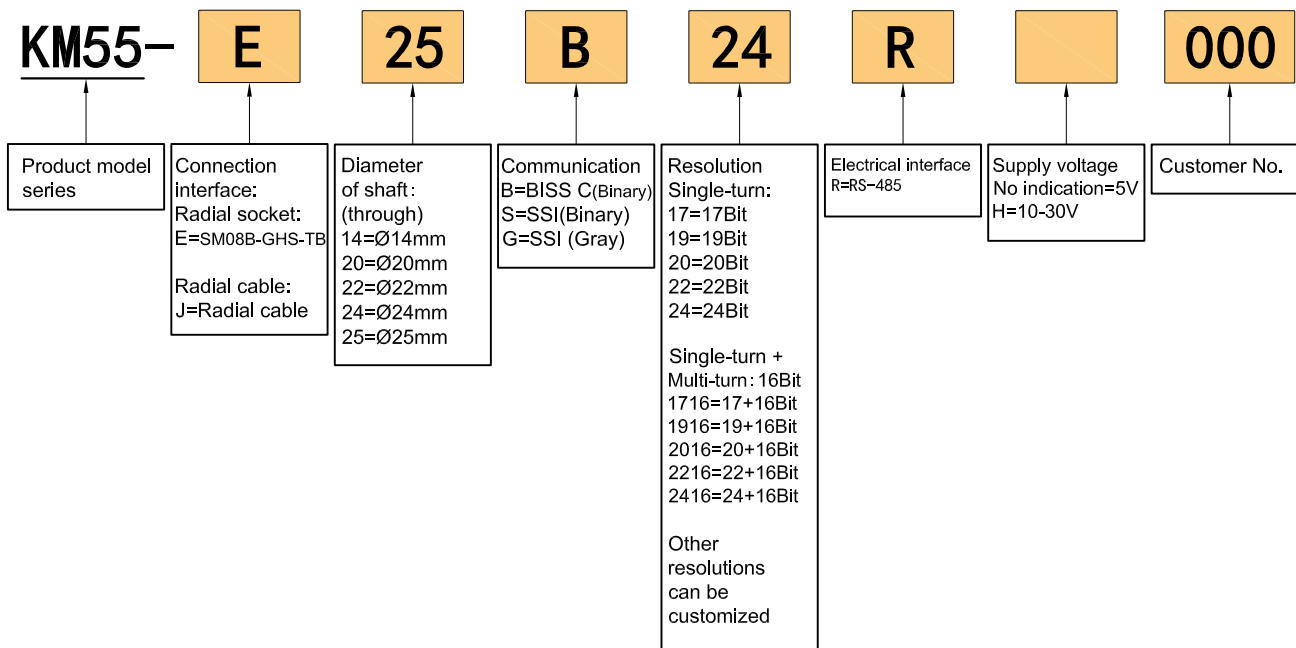
KM55-E



KM55-J



2. Model composition (select parameters)



3. Basic specification

3.1 Resolution

Single-turn(ST)		Multi-turn(MT)	
17Bits	$2^{17}(0\sim+131071)$	16Bits	$2^{16}(65536 \text{ turn})$
19Bits	$2^{19}(0\sim+524287)$	16Bits	$2^{16}(65536 \text{ turn})$
20Bits	$2^{20}(0\sim+1048575)$	16Bits	$2^{16}(65536 \text{ turn})$
22Bits	$2^{22}(0\sim+4194303)$	16Bits	$2^{16}(65536 \text{ turn})$
24Bits	$2^{24}(0\sim+16777215)$	16Bits	$2^{16}(65536 \text{ turn})$

Under 24Bits as standard, expandable up to Max 32Bits

16Bits is the standard product, others can be customized, Max 24Bits

3.2 Parameter

Name	Parameter	Remark
Scanning principle	Photoelectric	
Accuracy	$\pm 80''$	
Response speed	Normal action: 6000min^{-1}	
RMS position signal noise	$\pm 2 @ 18 \text{ Bits/r}$	
Communication	BiSS_C (Binary)	Pls refer to BiSS_C standards
	SSI (Binary / Gray code)	Pls refer to SSI standards
Communication clock frequency	$\leq 10 \text{ MHz(BiSS)}$ or $\leq 5 \text{ MHz(SSI)}$	
Max resolution	24 Bits expandable up to Max 32 Bits	For frame infomation,please refer to P9 & P10 (data frammes)
Starting time	Typical value: 13 ms	
Absolute position sampling period	$\leq 75 \text{ ns}$	
Allowable speed	$\leq 32200 \text{ r/min}$	Restricted by mechanical speed limit
Electrical connection	Radial socket & Radial cable	Pls refer to page 6、 7
Cable	Twisted-paired cable	
Cable length	200mm - 10000mm	
Internal single-turn position update rate	15000kHz	Access rate is limited by communication frequency
Internal multi-turn position update rate	11.5kHz	
Temperature alarm limit value	$-20^{\circ}\text{C}\sim 95^{\circ}\text{C}$	

3.3 Mechanical specification

Name	Parameter	Remark
Mechanical Connection	Ring locking with shaft, flexible spring plate fixed connection	
Diameter of shaft	Ø14mm、Ø20mm、Ø22mm、Ø24mm、Ø25mm (through)	Pls refer to page 5 for dimensions
Shaft material	Stainless steel	
Starting Torque	less than 9.8×10^{-3} N·m	
Inertia Moment	less than 6.5×10^{-6} kg·m ²	
Shaft load	Radial 30N; Axial 20N	
Allowed speed	≤6000 rpm	
Shell material	Aluminium alloy	
Weight	about 150g	

3.4 Environmental specification

Name	Parameter
Environmental temperature	Operating: -20~95°C
	Storage: -25~+95°C
Environmental humidity	Operating and storage:35~85%RH (Noncondensing)
Vibration	Amplitude 0.75mm ,5~55HZ,2h for X,Y,Z direction individually
Shock	490m/s ² 11ms three times for X,Y,Z direction individually
Protection	IP50

4. Electrical Characteristics

4.1 Absolute Maximum Ratings

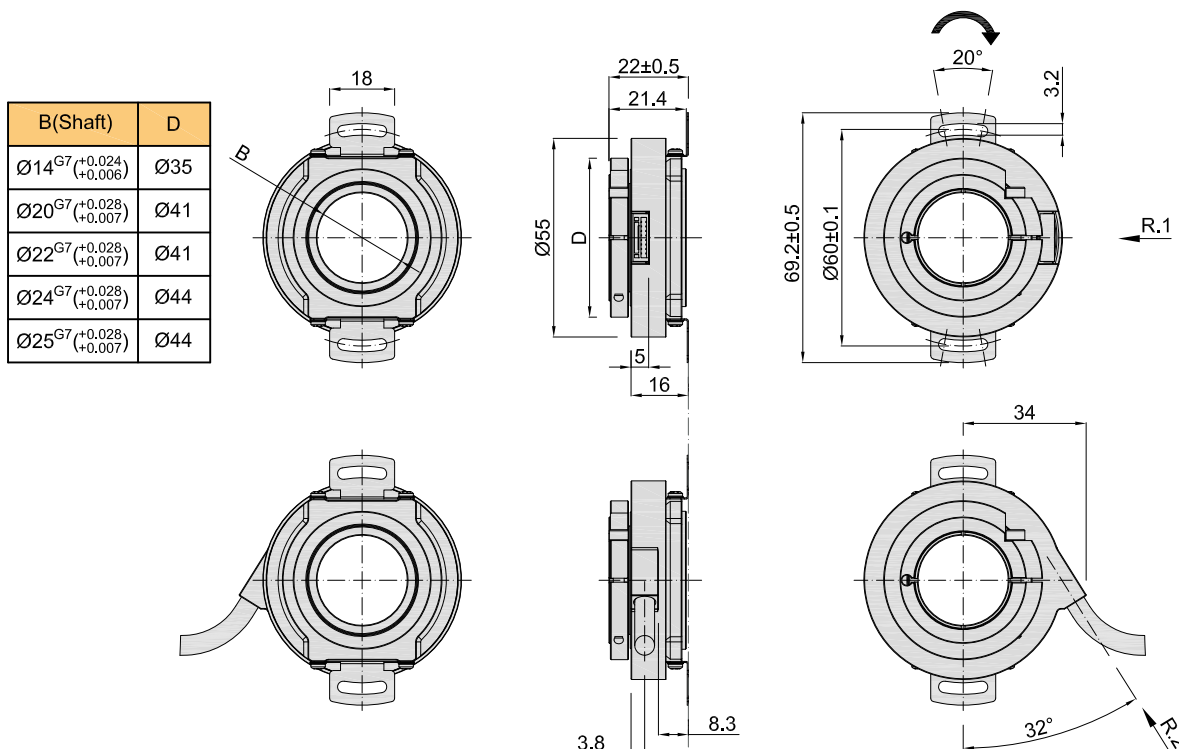
Symbol	Instructions	Minimum	Maximum	Unit
V _{CC}	Supply Voltage	-0.3	+6.0	V
V _{BAT}	Backup Voltage	-0.3	+6.0	V
T _{STG}	Storage Temperature	-20	+95	° C
T _J	Junction Temperature	-	150	° C

4.2 Recommended electrical parameter

Symbol	Instruction	Minimum	Typical value	Maximum	Unit
V _{CC}	Supply Voltage	4.75	5.0	5.5	V
I _{DD}	Supply Current	-	-	120	mA
V _{BAT}	Backup Voltage ①	3.0	3.6	4.2	V
I _(BAT)	Backup Current	-	-	35	uA
f _{BISS} ②	BISS Communication clock frequency	-	-	10	MHz
	SSI Communication clock frequency	-	-	5.0	MHz
T _a	Operating temperature	-20	-	+95	° C

- ① For the power supply sequence of multi-turn absolute encoders, be sure to power on the system after the battery has been powered up.
- ② Pls refer to BiSS_C and SSI standards.

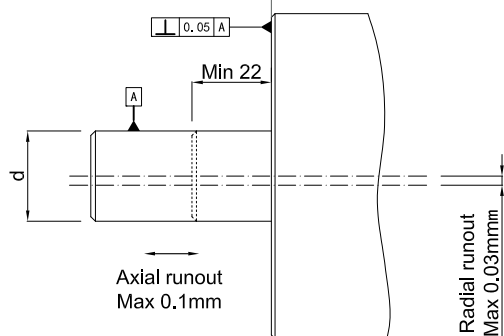
5. Basic dimensions



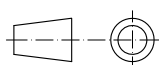
6. Specification for mounting shaft

Mounting screws
Inner hexagon bolt +flat washer Specification: M3*6 Material: stainless steel Quantity: 2

d
Ø14 _{g6} ^(-0.006/-0.017)
Ø20 _{g6} ^(-0.007/-0.020)
Ø22 _{g6} ^(-0.007/-0.020)
Ø24 _{g6} ^(-0.007/-0.020)
Ø25 _{g6} ^(-0.007/-0.020)







Unit: mm



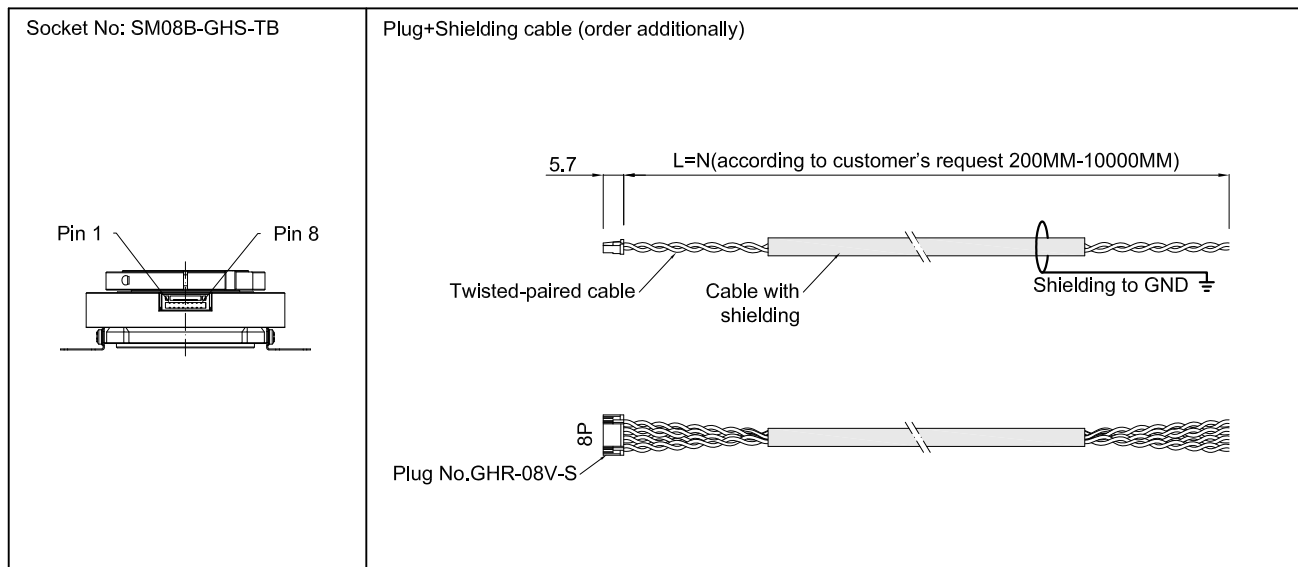
- = Shaft rotation direction of the signal output
- R. 1 = Radial socket(8P SM08B-GHS-TB)
- R. 2 = Radial cable (standard length 1000)

7. Interface Definition





7.1 Function and definition of socket pin (Radial socket)

Pin No.	Signal				Function	Twisted-paired cable
	BISS_C ST	BISS_C MT	SSI ST	SSI MT		
Pin 1	Up	Up	Up	Up	Power positive	
Pin 2	Un	Un	Un	Un	Power negative	
Pin 3	SL-	SL-	DATA-	DATA-	Data signal	
Pin 4	SL+	SL+	DATA+	DATA+	Data signal	
Pin 5	MA-	MA-	CLOCK-	CLOCK-	Clock signal	
Pin 6	MA+	MA+	CLOCK+	CLOCK+	Clock signal	
Pin 7	-	Vbat	-	Vbat	Backup power supply	
Pin 8	-	0V	-	0V	0V	

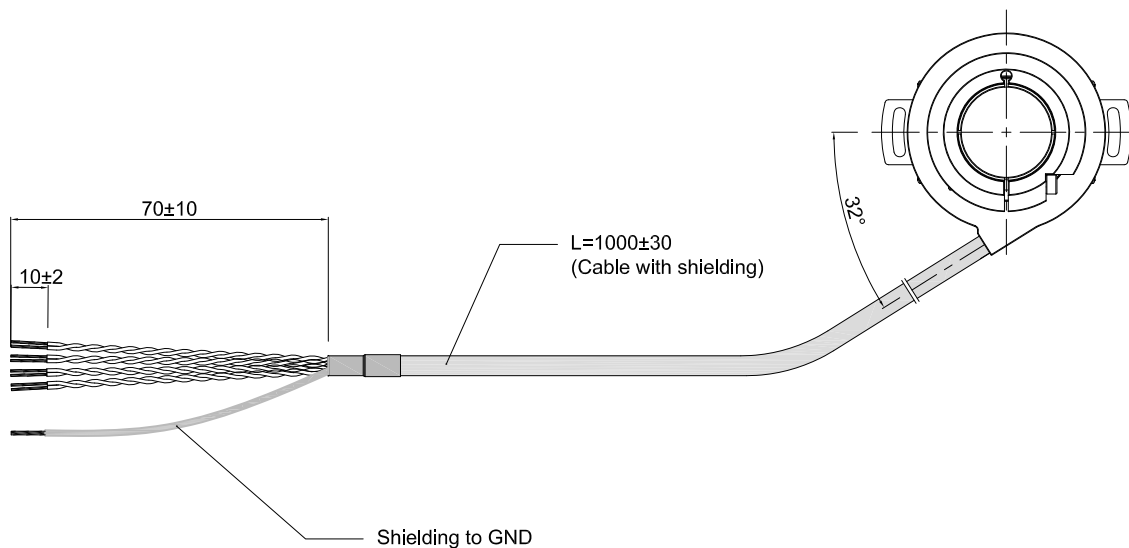
7.2 Pin Assignment



7.3 Function and color definition (Radial cable)

Wire Color	Signal				Function	Twisted-paired cable
	BISS_C ST	BISS_C MT	SSI ST	SSI MT		
Red	Up	Up	Up	Up	Power positive	
Black	Un	Un	Un	Un	Power negative	
White	SL-	SL-	DATA-	DATA-	Data signal	
White/black	SL+	SL+	DATA+	DATA+	Data signal	
Green	MA-	MA-	CLOCK-	CLOCK-	Clock signal	
Green/black	MA+	MA+	CLOCK+	CLOCK+	Clock signal	
Yellow	-	Vbat	-	Vbat	Back power supply	
Yellow/black	-	0V	-	0V	0V	

7.4 Radial cable schematic



Unit: mm

7.5 Electrical Connection

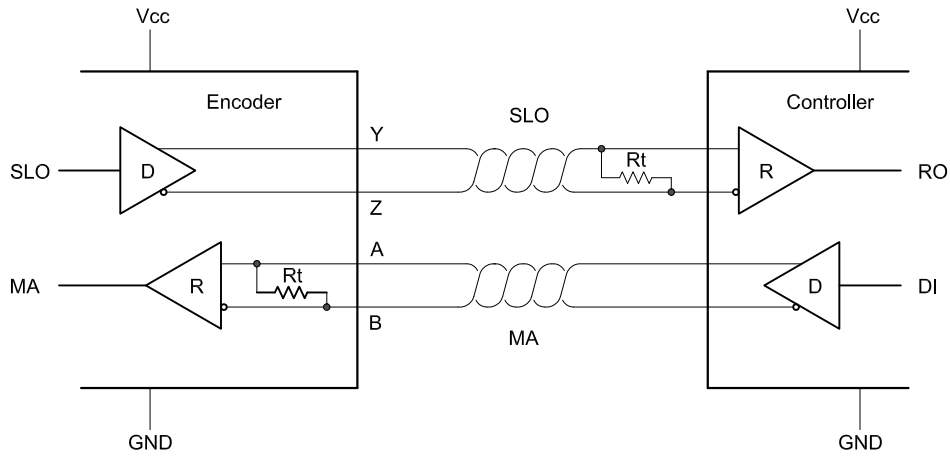


Figure 1: Point-to-point configuration

Note: Both the MA and SLQ lines are differential twisted-paired cable transmission, compatible with RS422.
The terminal resistor of the MA transmission line has been integrated inside the encoder.

7.6 BiSS_C Communication

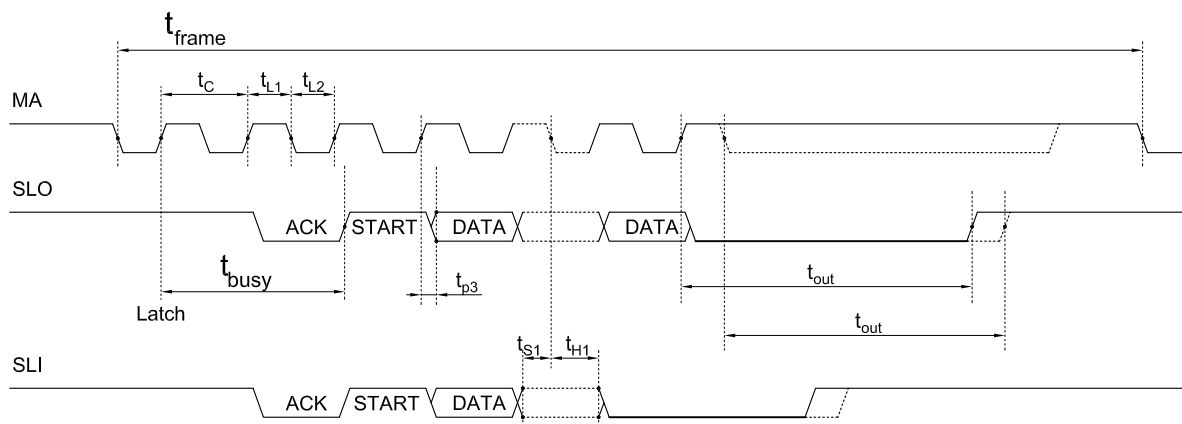


Figure 2: BiSS-C Timing

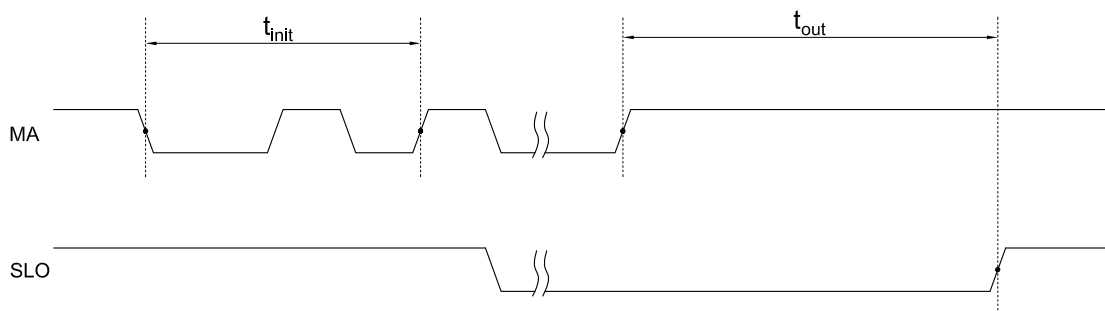


Figure 3: BiSS-C (SSI) Slave Timeout Sequence

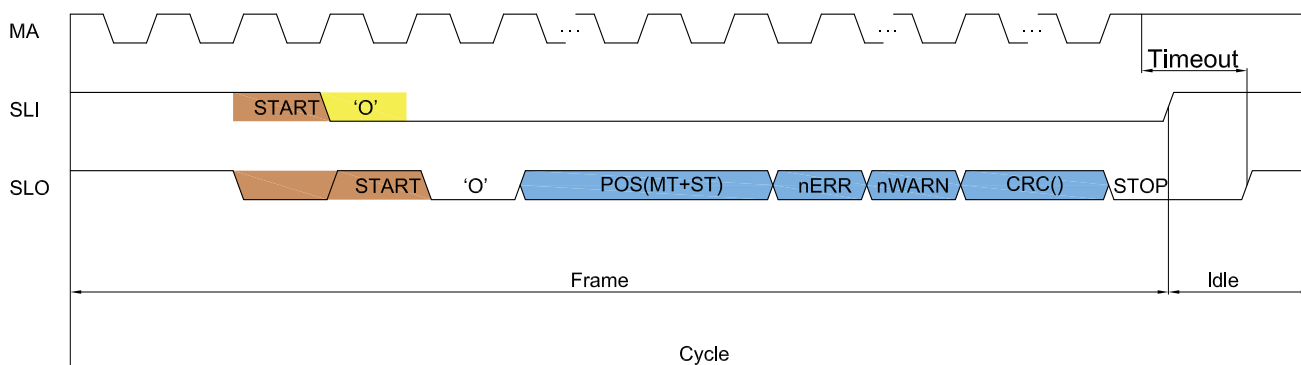


Figure 4: BiSS Frame Structure

7.7 SSI Communication

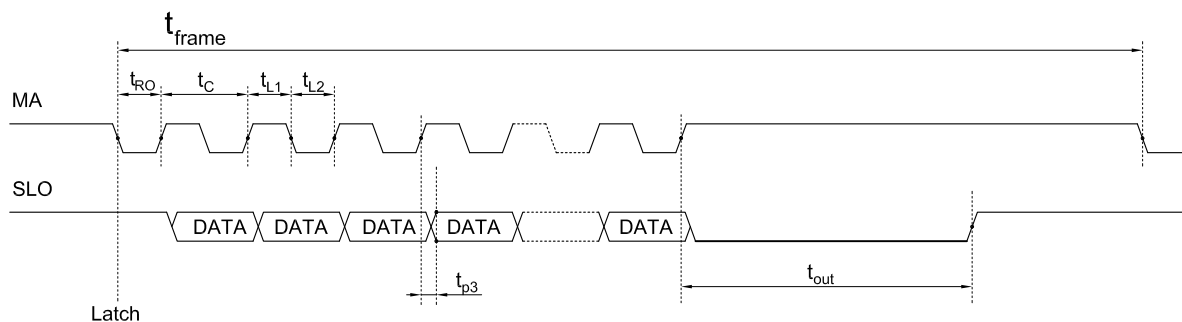


Figure 5: SSI Timing

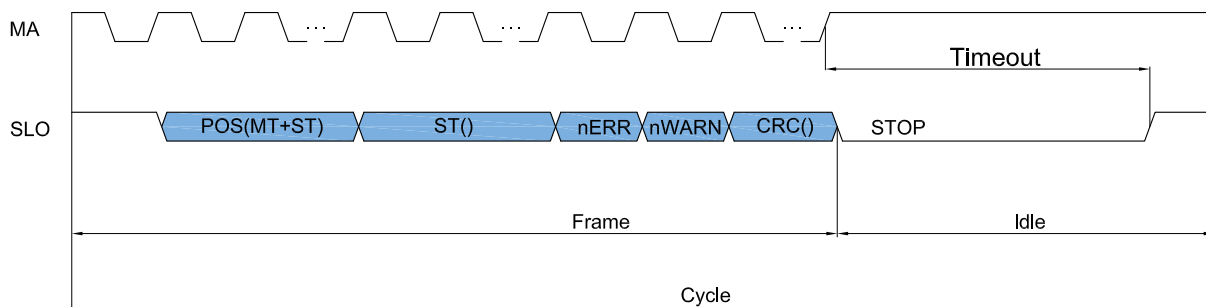


Figure 6: SSI Frame Structure

The frame is composed of frame structure and data to be transmitted. The sequence of data transmission first is MSB, error bit and alarm bit are low effective, cyclic redundancy check transmitted inverted. The specific data composition is shown in the below table:

Bits No.	Data	Instructions
[55:32]	MT[23:0]	Recording the accumulative number of the encoder running after power on, including directivity
[31:8]	ST[23:0]	Current data of absolute location
[7]	nERR	Error output, active low
[6]	nWARN	Warning output, active low
[5:0]	CRC[5:0]	Check bit CRC polynomial of 0x43 with a starting value of 0 (output at flip level)

8. Caution

8.1 Caution for operation

- The working temperature shall not exceed the storage temperature.
- The working humidity shall not exceed the storage humidity.
- Do not use where the temperature changes dramatically and have fog.
- Do not close to corrosive and flammable gas.
- Keep away from dust, salt and metal powder.
- Keep away from places where you will use water, oil, or medicine.
- Undue vibration and shock will impact the encoder.

8.2 Caution for Installation

- Electrical components should not be subjected to excessive pressure, etc., and electrostatic assessment of the installation environment should be conducted.
- Do not close the cable of the motor power to the encoder.
- The FG wire of the motor and mechanical device should be grounded.
- The shielding wire must be effectively grounded since the shielding is not connected to the encoder.

8.3 Caution for wiring

- Use the encoder under the specified supply voltage. Please note that the supply voltage range may drop due to the wiring length.
- Do not put the encoder wiring and other power lines through the same duct, and do not use them by bundling in parallel.
- Please use twisted pair wires for the signal and power wires of encoder.
- Please do not apply excessive force to the cable of encoder, or it will may be damaged.